# Hydrodynamization and Attractors at Intermediate Coupling 

Jorge Casalderrey-Solana<br>Nikola Gushterov<br>Ben Meiring*

University of Oxford
ben.meiring@physics.ox.ac.uk

July 2018

## Motivation \& Questions

- Why does Hydrodynamics work outside it's regime of applicability?


## Motivation \& Questions

- Why does Hydrodynamics work outside it's regime of applicability?
- What qualitative changes do we observe as we interpolate between gauge theories at infinite and finite coupling?


## Motivation \& Questions

- Why does Hydrodynamics work outside it's regime of applicability?
- What qualitative changes do we observe as we interpolate between gauge theories at infinite and finite coupling?
We will be studying the $T_{\mu \nu}$ of strongly coupled, conformal, boost invariant field theories that relax to Bjorken Flow at late times. Our Paper: [1712.02772]


## Motivation \& Questions

- Why does Hydrodynamics work outside it's regime of applicability?
- What qualitative changes do we observe as we interpolate between gauge theories at infinite and finite coupling?

We will be studying the $T_{\mu \nu}$ of strongly coupled, conformal, boost invariant field theories that relax to Bjorken Flow at late times. Our Paper: [1712.02772]

This amounts to studying the Anisotropy $R(w)$ as a function of the dimensionless parameter $w=\tau T$.

$$
\begin{equation*}
R(w)=\frac{P_{T}-P_{L}}{P_{\mathrm{Tot}}} \tag{1}
\end{equation*}
$$

## Cartoon of Heavy Ion Collision: Scenario 1



Figure: Early system dynamics has a microscopic description that relaxes to a common curve, called the Attractor. The late time dynamics should be described by Hydrodynamics when gradients are small $(w=\tau T>1)$.

## Cartoon of Heavy Ion Collision: Scenario 1



Figure: Early system dynamics has a microscopic description that relaxes to a common curve, called the Attractor. The late time dynamics should be described by Hydrodynamics when gradients are small $(w=\tau T>1)$.

## Cartoon of Heavy Ion Collision: Scenario 1



Figure: Early system dynamics has a microscopic description that relaxes to a common curve, called the Attractor. The late time dynamics should be described by Hydrodynamics when gradients are small $(w=\tau T>1)$.

## Cartoon of Heavy Ion Collision: Scenario 2



Figure: Early system dynamics has a microscopic description that relaxes to a common curve, called the Attractor. The late time dynamics should be described by Hydrodynamics when gradients are small $(w=\tau T>1)$.

## Problem Set-up

- We will use Gauss-Bonnet Gravity (a higher derivative theory of gravity) to study gauge theories at intermediate coupling through the Gauge-Gravity duality.


## Problem Set-up

- We will use Gauss-Bonnet Gravity (a higher derivative theory of gravity) to study gauge theories at intermediate coupling through the Gauge-Gravity duality.
- One can find,

$$
\begin{equation*}
\frac{\eta}{s}=\frac{1-\lambda_{G B}}{4 \pi} \tag{2}
\end{equation*}
$$

where $\lambda_{G B}$ is a parameter of the theory we can tune to pick out our preferred coupling.
The case $\lambda_{G B}=0$ is Einstein Gravity ( $\mathcal{N}=4$ SYM) and was studied by M. Heller, R. Janik, P. Witaszczyk. 2013.

## Problem Set-up

- We will use Gauss-Bonnet Gravity (a higher derivative theory of gravity) to study gauge theories at intermediate coupling through the Gauge-Gravity duality.
- One can find,

$$
\begin{equation*}
\frac{\eta}{s}=\frac{1-\lambda_{G B}}{4 \pi} \tag{2}
\end{equation*}
$$

where $\lambda_{G B}$ is a parameter of the theory we can tune to pick out our preferred coupling.
The case $\lambda_{G B}=0$ is Einstein Gravity ( $\mathcal{N}=4$ SYM) and was studied by M. Heller, R. Janik, P. Witaszczyk. 2013.

- We calculate the hydrodynamic expansion for the Anisotropy $R(w)$, where powers of $w^{-1}=\frac{1}{\tau T}$ corresponds to orders in gradients:

$$
\begin{equation*}
R(w)=\underbrace{r_{1} w^{-1}}_{\substack{1^{\text {st }} \text { order } \\ \text { viscous hydro }}}+\underbrace{r_{2} w^{-2}+r_{3} w^{-3}+\ldots}_{\text {Further gradient corrections }} \tag{3}
\end{equation*}
$$

## Gravity Solution \& Hydrodynamics

The Action for Gauss-Bonnet Gravity is given by,

$$
S=\int d^{5} x \sqrt{-g}\left(R+12+\frac{\lambda_{G B}}{2}\left(R_{\mu \nu \rho \sigma} R^{\mu \nu \rho \sigma}-4 R_{\mu \nu} R^{\mu \nu}+R^{2}\right)\right) .
$$

## Gravity Solution \& Hydrodynamics

The Action for Gauss-Bonnet Gravity is given by,

$$
S=\int d^{5} x \sqrt{-g}\left(R+12+\frac{\lambda_{G B}}{2}\left(R_{\mu \nu \rho \sigma} R^{\mu \nu \rho \sigma}-4 R_{\mu \nu} R^{\mu \nu}+R^{2}\right)\right) .
$$

the solution takes the form of a power series in inverse proper time $\tau^{-2 / 3}$ :

$$
\begin{equation*}
d s^{2}=-r^{2} A(r, \tau) d \tau^{2}+2 d \tau d r+(1+r \tau)^{2} e^{b} d y^{2}+r^{2} e^{d-\frac{1}{2} b} d x_{\perp}^{2} \tag{4}
\end{equation*}
$$

where

$$
\begin{array}{ll}
A(\tau, r)=\sum_{i=0} u^{i} A_{i}(s) & , s=r^{-1} \tau^{-1 / 3} \\
b(\tau, r)=\sum_{i=0} u^{i} b_{i}(s) & , u=\tau^{-2 / 3} \\
d(\tau, r)=\sum_{i=0} u^{i} d_{i}(s) &
\end{array}
$$

## Gravity Solution \& Hydrodynamics

The Action for Gauss-Bonnet Gravity is given by,

$$
S=\int d^{5} x \sqrt{-g}\left(R+12+\frac{\lambda_{G B}}{2}\left(R_{\mu \nu \rho \sigma} R^{\mu \nu \rho \sigma}-4 R_{\mu \nu} R^{\mu \nu}+R^{2}\right)\right) .
$$

the solution takes the form of a power series in inverse proper time $\tau^{-2 / 3}$ :

$$
\begin{equation*}
d s^{2}=-r^{2} A(r, \tau) d \tau^{2}+2 d \tau d r+(1+r \tau)^{2} e^{b} d y^{2}+r^{2} e^{d-\frac{1}{2} b} d x_{\perp}^{2} \tag{4}
\end{equation*}
$$

where

$$
\begin{array}{ll}
A(\tau, r)=\sum_{i=0} u^{i} A_{i}(s) & , s=r^{-1} \tau^{-1 / 3} \\
b(\tau, r)=\sum_{i=0} u^{i} b_{i}(s) & , u=\tau^{-2 / 3} \\
d(\tau, r)=\sum_{i=0} u^{i} d_{i}(s) &
\end{array}
$$

From which we can find the Energy Density

$$
\epsilon(u)=u^{2}\left(\epsilon_{0}+\epsilon_{1} u+\epsilon_{2} u^{2}+\epsilon_{3} u^{3}+\ldots\right)
$$

## Gravity Solution \& Hydrodynamics

The Action for Gauss-Bonnet Gravity is given by,

$$
S=\int d^{5} x \sqrt{-g}\left(R+12+\frac{\lambda_{G B}}{2}\left(R_{\mu \nu \rho \sigma} R^{\mu \nu \rho \sigma}-4 R_{\mu \nu} R^{\mu \nu}+R^{2}\right)\right),
$$

the solution takes the form of a power series in inverse proper time $\tau^{-2 / 3}$ :

$$
\begin{equation*}
d s^{2}=-r^{2} A(r, \tau) d \tau^{2}+2 d \tau d r+(1+r \tau)^{2} e^{b} d y^{2}+r^{2} e^{d-\frac{1}{2} b} d x_{\perp}^{2} \tag{5}
\end{equation*}
$$

where

$$
\begin{array}{lr}
A(\tau, r)=\sum_{i=0} u^{i} A_{i}(s) & , s=r^{-1} \tau^{-1 / 3} \\
b(\tau, r)=\sum_{i=0} u^{i} b_{i}(s) \quad, u=\tau^{-2 / 3} \\
d(\tau, r)=\sum_{i=0} u^{i} d_{i}(s) &
\end{array}
$$

From which we can find the Energy Density

$$
\epsilon(u)=u^{2}\left(\epsilon_{0}+\epsilon_{1} u+\epsilon_{2} u^{2}+\epsilon_{3} u^{3}+\ldots\right)
$$

## Gravity Solution \& Hydrodynamics

The Action for Gauss-Bonnet Gravity is given by,

$$
S=\int d^{5} x \sqrt{-g}\left(R+12+\frac{\lambda_{G B}}{2}\left(R_{\mu \nu \rho \sigma} R^{\mu \nu \rho \sigma}-4 R_{\mu \nu} R^{\mu \nu}+R^{2}\right)\right),
$$

the solution takes the form of a power series in inverse proper time $\tau^{-2 / 3}$ :

$$
\begin{equation*}
d s^{2}=-r^{2} A(r, \tau) d \tau^{2}+2 d \tau d r+(1+r \tau)^{2} e^{b} d y^{2}+r^{2} e^{d-\frac{1}{2} b} d x_{\perp}^{2} \tag{6}
\end{equation*}
$$

where

$$
\begin{array}{lr}
A(\tau, r)=\sum_{i=0} u^{i} A_{i}(s) & , s=r^{-1} \tau^{-1 / 3} \\
b(\tau, r)=\sum_{i=0} u^{i} b_{i}(s) & , u=\tau^{-2 / 3} \\
d(\tau, r)=\sum_{i=0} u^{i} d_{i}(s) &
\end{array}
$$

From which we can find the Energy Density

$$
\epsilon(u)=u^{2}\left(\epsilon_{0}+\epsilon_{1} u+\epsilon_{2} u^{2}+\epsilon_{3} u^{3}+\ldots\right)
$$

## Gravity Solution \& Hydrodynamics

The Action for Gauss-Bonnet Gravity is given by,

$$
S=\int d^{5} x \sqrt{-g}\left(R+12+\frac{\lambda_{G B}}{2}\left(R_{\mu \nu \rho \sigma} R^{\mu \nu \rho \sigma}-4 R_{\mu \nu} R^{\mu \nu}+R^{2}\right)\right),
$$

the solution takes the form of a power series in inverse proper time $\tau^{-2 / 3}$ :

$$
\begin{equation*}
d s^{2}=-r^{2} A(r, \tau) d \tau^{2}+2 d \tau d r+(1+r \tau)^{2} e^{b} d y^{2}+r^{2} e^{d-\frac{1}{2} b} d x_{\perp}^{2} \tag{7}
\end{equation*}
$$

where

$$
\begin{array}{ll}
A(\tau, r)=\sum_{i=0} u^{i} A_{i}(s) & , s=r^{-1} \tau^{-1 / 3} \\
b(\tau, r)=\sum_{i=0} u^{i} b_{i}(s) & , u=\tau^{-2 / 3} \\
d(\tau, r)=\sum_{i=0} u^{i} d_{i}(s) &
\end{array}
$$

From which we can find the Energy Density $\rightarrow$ Anisotropy

$$
\epsilon(u) \rightarrow R(w)=r_{1} w+r_{2} w^{2}+r_{3} w^{3}+\ldots \quad, \quad w=\frac{1}{\tau T}
$$

## Resurgence

The coefficients $r_{n}$ calculated from our gravity solution shows that each Hydrodynamic series does not converge.


Figure: Anisotropy coefficients showing $r_{n} \sim n$ ! as a function of order $n . r_{n}$ are displayed for $\lambda_{G B}=0,-0.1,-0.2,-0.5$, and -1 .

## Resurgence

We rewrite the divergent series a Laplace Transform,

$$
\begin{aligned}
R(w) & =r_{1} w^{-1}+r_{2} w^{-2}+r_{3} w^{-3}+\ldots \\
& =w \int_{0}^{\infty e^{i \theta}} d u e^{-u w} \underbrace{\left(\frac{r_{1}}{1!} w^{-1}+\frac{r_{2}}{2!} w^{-2}+\frac{r_{3}}{3!} w^{-3}+\ldots\right)}_{\text {The Borel Transform } R_{B}(u)}
\end{aligned}
$$

## Resurgence

We rewrite the divergent series a Laplace Transform,

$$
\begin{aligned}
R(w) & =r_{1} w^{-1}+r_{2} w^{-2}+r_{3} w^{-3}+\ldots \\
& =w \int_{0}^{\infty e^{i \theta}} d u e^{-u w} \underbrace{\left(\frac{r_{1}}{1!} w^{-1}+\frac{r_{2}}{2!} w^{-2}+\frac{r_{3}}{3!} w^{-3}+\ldots\right)}_{\text {The Borel Transform } R_{B}(u)}
\end{aligned}
$$

Any Laplace transform of the Pade Approximant of $R_{B}(w)$ is meant to be a valid solution, which means that to the linearized level the difference between two contours will also be a solution.


## Resurgence

We rewrite the divergent series a Laplace Transform,

$$
\begin{aligned}
R(w) & =r_{1} w^{-1}+r_{2} w^{-2}+r_{3} w^{-3}+\ldots \\
& =w \int_{0}^{\infty e^{i \theta}} d u e^{-u w} \underbrace{\left(\frac{r_{1}}{1!} w^{-1}+\frac{r_{2}}{2!} w^{-2}+\frac{r_{3}}{3!} w^{-3}+\ldots\right)}_{\text {The Borel Transform } R_{B}(u)}
\end{aligned}
$$

Any Laplace transform of the Pade Approximant of $R_{B}(w)$ is meant to be a valid solution, which means that to the linearized level the difference between two contours will also be a solution.


## Resurgence



Figure: Choosing one contour leads to one particular evolution. Including linear combinations of the non-hydrodynamic solutions leads to a characteristic spread of solutions. These different choices amount to assigning different initial data to the system.

## Resurgence



Figure: Choosing one contour leads to one particular evolution. Including linear combinations of the non-hydrodynamic solutions leads to a characteristic spread of solutions. These different choices amount to assigning different initial data to the system.

## Resurgence



Figure: Resummed $R(w)$ plus non-hydrodynamic solutions with varied initial conditions. We define the Hydrodynamization Time as the $w$ where $R(w)$ deviates from it's first order truncation by $10 \%$. $1^{\text {st }}$ order hydro is given by the red dashed curve.

## What are these Transient Modes?



Figure: Non-hydrodynamic information is encoded in the poles (grey dots) of $R_{B}(u)$ for $\lambda_{G B}=0, \mathrm{M}$. Heller, R. Janik, P. Witaszczyk. 2013. We can identify QNM's (colourful dots) as the non-hydrodynamic modes of the microscopic theory, computed by A. Starinets. 2002.

## What are these Transient Modes?

These poles show up in the Borel Plane because the true solution has the form,

$$
\begin{aligned}
A(\tau, r) & =\sum_{i=0} u^{i} A_{i}^{\mathbf{0}}(s)+\sum_{\boldsymbol{n} \in \mathbb{N}^{\infty}} \Omega_{\boldsymbol{n}}(u) \sum_{i=0} u^{i} A_{i}^{n}(s), \\
b(\tau, r) & =\sum_{i=0} u^{i} b_{i}^{\mathbf{0}}(s)+\sum_{\boldsymbol{n} \in \mathbb{N}^{\infty}} \Omega_{\boldsymbol{n}}(u) \sum_{i=0} u^{i} b_{i}^{\boldsymbol{n}}(s), \\
d(\tau, r) & =\sum_{i=0} u^{i} d_{i}^{\mathbf{0}}(s)+\sum_{\boldsymbol{n} \in \mathbb{N}^{\infty}} \Omega_{\boldsymbol{n}}(u) \sum_{i=0} u^{i} d_{i}^{\boldsymbol{n}}(s),
\end{aligned}
$$

with $\Omega_{\boldsymbol{n}}(u)=u^{\boldsymbol{n} \cdot \boldsymbol{\alpha}} e^{-\boldsymbol{n} \cdot \boldsymbol{\omega} / u}$ a function non-perturbative in small $u$, and $\omega$ giving the spectrum of Quasinormal Mode frequencies.

## What are these Transient Modes?

These poles show up in the Borel Plane because the true solution has the form,

$$
\begin{aligned}
A(\tau, r) & =\sum_{i=0} u^{i} A_{i}^{0}(s)+\sum_{\boldsymbol{n} \in \mathbb{N}^{\infty}} \Omega_{\boldsymbol{n}}(u) \sum_{i=0} u^{i} A_{i}^{n}(s), \\
b(\tau, r) & =\sum_{i=0} u^{i} b_{i}^{\mathbf{0}}(s)+\sum_{\boldsymbol{n} \in \mathbb{N}^{\infty}} \Omega_{\boldsymbol{n}}(u) \sum_{i=0} u^{i} b_{i}^{\boldsymbol{n}}(s), \\
d(\tau, r) & =\sum_{i=0} u^{i} d_{i}^{\mathbf{0}}(s)+\sum_{\boldsymbol{n} \in \mathbb{N}^{\infty}} \Omega_{\boldsymbol{n}}(u) \sum_{i=0} u^{i} d_{i}^{\boldsymbol{n}}(s),
\end{aligned}
$$

with $\Omega_{\boldsymbol{n}}(u)=u^{\boldsymbol{n} \cdot \boldsymbol{\alpha}} e^{-\boldsymbol{n} \cdot \boldsymbol{\omega} / u}$ a function non-perturbative in small $u$, and $\omega$ giving the spectrum of Quasinormal Mode frequencies.

- Functions $A_{i}^{\mathbf{0}}(s), b_{i}^{\mathbf{0}}(s) \& d_{i}^{0}(s)$ are the same perturbative expansion as before.


## What are these Transient Modes?

These poles show up in the Borel Plane because the true solution has the form,

$$
\begin{aligned}
A(\tau, r) & =\sum_{i=0} u^{i} A_{i}^{0}(s)+\sum_{n \in \mathbb{N}^{\infty}} \Omega_{n}(u) \sum_{i=0} u^{i} A_{i}^{n}(s) \\
b(\tau, r) & =\sum_{i=0} u^{i} b_{i}^{\mathbf{0}}(s)+\sum_{\boldsymbol{n} \in \mathbb{N}^{\infty}} \Omega_{n}(u) \sum_{i=0} u^{i} b_{i}^{\boldsymbol{n}}(s) \\
d(\tau, r) & =\sum_{i=0} u^{i} d_{i}^{\mathbf{0}}(s)+\sum_{n \in \mathbb{N}^{\infty}} \Omega_{n}(u) \sum_{i=0} u^{i} d_{i}^{n}(s)
\end{aligned}
$$

- Functions $A_{i}^{\mathbf{0}}(s), b_{i}^{\mathbf{0}}(s) \& d_{i}^{\mathbf{0}}(s)$ are the same perturbative expansion as before.
- $\Omega_{n}(u)=u^{n \cdot \alpha} e^{-n \cdot \omega / u}$ are non-perturbative functions in small $u$, and $\omega$ gives the spectrum of Quasinormal Mode frequencies.


## What are these Transient Modes?

These poles show up in the Borel Plane because the true solution has the form,

$$
\begin{aligned}
& A(\tau, r)=\sum_{i=0} u^{i} A_{i}^{\mathbf{0}}(s)+\sum_{n \in \mathbb{N}^{\infty}} \Omega_{n}(u) \sum_{i=0} u^{i} A_{i}^{n}(s), \\
& b(\tau, r)=\sum_{i=0} u^{i} b_{i}^{\mathbf{0}}(s)+\sum_{n \in \mathbb{N}^{\infty}} \Omega_{n}(u) \sum_{i=0} u^{i} b_{i}^{n}(s) \\
& d(\tau, r)=\sum_{i=0} u^{i} d_{i}^{\mathbf{0}}(s)+\sum_{n \in \mathbb{N}^{\infty}} \Omega_{n}(u) \sum_{i=0} u^{i} d_{i}^{n}(s),
\end{aligned}
$$

- Functions $A_{i}^{\mathbf{0}}(s), b_{i}^{\mathbf{0}}(s) \& d_{i}^{\mathbf{0}}(s)$ are the same perturbative expansion as before.
- $\Omega_{n}(u)=u^{\boldsymbol{n} \cdot \alpha} e^{-\boldsymbol{n} \cdot \boldsymbol{\omega} / u}$ are non-perturbative functions in small $u$, and $\omega$ gives the spectrum of Quasinormal Mode frequencies.
(See talk by Jakub Jankowski where we've calculated the "Non-hydrodynamic" gradient expansion for some sectors in collaboration with Inês Aniceto \& Michał Spalińksi).


## What are these Transient Modes?



Figure: Non-hydrodynamic information is encoded in the poles (grey dots) of $R_{B}(u)$ for $\lambda_{G B}=0, \mathrm{M}$. Heller, R. Janik, P. Witaszczyk. 2013. We can identify QNM's (colourful dots) as the non-hydrodynamic modes of the microscopic theory, computed by A. Starinets. 2002.

## Intermediate Coupling Effects



Figure: Non-hydrodynamic information is encoded in the poles (grey dots) of $R_{B}(u)$ for $\lambda_{G B}=-0.1$. We can identify QNM's (colourful dots) as the non-hydrodynamic modes of the microscopic theory, computed by S . Grozdanov, N. Kaplis, A. O. Starinets. 2016.

## Intermediate Coupling Effects



Figure: Non-hydrodynamic information is encoded in the poles (grey dots) of $R_{B}(u)$ for $\lambda_{G B}=-0.2$. We can identify QNM's (colourful dots) as the non-hydrodynamic modes of the microscopic theory, computed by S . Grozdanov, N. Kaplis, A. O. Starinets. 2016.

## Intermediate Coupling Effects



Figure: Non-hydrodynamic information is encoded in the poles (grey dots) of $R_{B}(u)$ for $\lambda_{G B}=-0.5$. We can identify QNM's (colourful dots) as the non-hydrodynamic modes of the microscopic theory, computed by S . Grozdanov, N. Kaplis, A. O. Starinets. 2016.

## Intermediate Coupling Effects



Figure: Non-hydrodynamic information is encoded in the poles (grey dots) of $R_{B}(u)$ for $\lambda_{G B}=-1$. We can identify QNM's (colourful dots) as the non-hydrodynamic modes of the microscopic theory, computed by S . Grozdanov, N. Kaplis, A. O. Starinets. 2016.

## Intermediate Coupling Effects



Figure: Applying similar methodology in the case of finite coupling, we can estimate the characteristic spread of solutions as they decay to the attractor. In all cases we study the result is well approximated by $1^{\text {st }}$ order hydrodynamics (red dashed line).

## How else can we study Bjorken Flow in $\mathcal{N}=4$ SYM?

Do we have any other expansion parameters we can use to solve this system? [Ongoing work with Jorge Casalderrey-Solana \& Chris Herzog]

$$
\begin{equation*}
d s_{5}^{2}=-A d t^{2}+2 d r d \tau+S^{2}\left(e^{-2 B} d y^{2}+e^{B} d x_{\perp}^{2}\right), \tag{8}
\end{equation*}
$$

where $A, B$ and $S$ are functions of $r$ and $\tau$.

## How else can we study Bjorken Flow in $\mathcal{N}=4$ SYM?

Do we have any other expansion parameters we can use to solve this system? [Ongoing work with Jorge Casalderrey-Solana \& Chris Herzog]

$$
\begin{equation*}
d s_{5}^{2}=-A d t^{2}+2 d r d \tau+S^{2}\left(e^{-2 B} d y^{2}+e^{B} d x_{\perp}^{2}\right) \tag{8}
\end{equation*}
$$

where $A, B$ and $S$ are functions of $r$ and $\tau$.
We can study Bjorken Flow in $n$ dimensions, and use $1 / n$ as an expansion parameter when $n$ is large.

$$
\begin{equation*}
d s^{2}=-A d \tau^{2}+2 d \tau d r+S^{2}\left(e^{-(n-2) B} d y^{2}+e^{B} d x_{\perp}^{2}\right) \tag{9}
\end{equation*}
$$

## Bjorken Flow in large dimensions $d=n+1$

In the large dimension limit, gravity backgrounds look flat with small corrections.


Black-brane in $d=5$
Black-brane in $d=\infty$

## Bjorken Flow in large dimensions $d=n+1$

In the large dimension limit, gravity backgrounds look flat with small corrections.


Black-brane in $d=5$


Black-brane in $d=\infty$

We fix $R=r^{n}$ and use an Ansatz given on the right hand side. The functions factored out from the sum give the flat space solution in $n$ dimensions, and the power series' in $1 / n$ gives finite $n$ corrections.

$$
\begin{aligned}
& A=r^{2} \sum_{i=0}^{\infty} \frac{1}{n^{i}} A_{i}(R, \tau) \\
& S=r^{\frac{n-2}{n-1}}(1+r \tau)^{\frac{1}{n-1}} \sum_{i=0}^{\infty} \frac{1}{n^{i}} S_{i}(R, \tau) \\
& B=\frac{2}{n-1} \log \left(\frac{r}{1+r \tau}\right) \sum_{i=0}^{\infty} \frac{1}{n^{i}} B_{i}(R, \tau) .
\end{aligned}
$$

## Bjorken Flow in large dimensions $d=n+1$

In the large dimension limit, gravity backgrounds look flat with small corrections.


Black-brane in $d=5$


Black-brane in $d=\infty$

We fix $R=r^{n}$ and use an Ansatz given on the right hand side. The functions factored out from the sum give the flat space solution in $n$ dimensions, and the power series' in $1 / n$ gives finite $n$ corrections.

$$
\begin{aligned}
& A=r^{2} \sum_{i=0}^{\infty} \frac{1}{n^{i}} A_{i}(R, \tau) \\
& S=r^{\frac{n-2}{n-1}}(1+r \tau)^{\frac{1}{n-1}} \sum_{i=0}^{\infty} \frac{1}{n^{i}} S_{i}(R, \tau) \\
& B=\frac{2}{n-1} \log \left(\frac{r}{1+r \tau}\right) \sum_{i=0}^{\infty} \frac{1}{n^{i}} B_{i}(R, \tau) .
\end{aligned}
$$

## Bjorken Flow in large dimensions $d=n+1$

In the large dimension limit, the gravity background is essentially flat with small corrections.


Black-brane in $d=5$


Black-brane in $d=\infty$

We fix $R=r^{n}$ and use an Ansatz given on the right hand side. The functions factored out from the sum give the flat space solution in $n$ dimensions, and the power series' in $1 / n$ gives finite $n$ corrections.

$$
\begin{aligned}
& A=r^{2} \sum_{i=0}^{\infty} \frac{1}{n^{i}} A_{i}(R, \tau) \\
& S=r^{\frac{n-2}{n-1}}(1+r \tau)^{\frac{1}{n-1}} \sum_{i=0}^{\infty} \frac{1}{n^{i}} S_{i}(R, \tau) \\
& B=\frac{2}{n-1} \log \left(\frac{r}{1+r \tau}\right) \sum_{i=0}^{\infty} \frac{1}{n^{i}} B_{i}(R, \tau) .
\end{aligned}
$$

## Bjorken Flow in large dimensions $d=n+1$

We have calculated these corrections to order $O\left(n^{-3}\right)$. At leading and subleading order they are given by,

$$
\begin{array}{ll}
S_{0}=1, & S_{1}=0 \\
A_{0}=1-\frac{\epsilon}{(1+\tau)} \frac{1}{R}, & A_{1}=\frac{\epsilon \log (1+\tau)}{(1+\tau)} \frac{1}{R}-\frac{\epsilon}{(1+\tau)^{2}} \frac{\log R}{R} \\
B_{0}=1 . & B_{1}=0
\end{array}
$$

with $R=r^{n}$, and $\epsilon$ a constant of integration that turns out to be the energy density.

## Bjorken Flow in large dimensions $d=n+1$

We have calculated these corrections to order $O\left(n^{-3}\right)$. At leading and subleading order they are given by,

$$
\begin{array}{ll}
S_{0}=1, & S_{1}=0 \\
A_{0}=1-\frac{\epsilon}{(1+\tau)} \frac{1}{R}, & A_{1}=\frac{\epsilon \log (1+\tau)}{(1+\tau)} \frac{1}{R}-\frac{\epsilon}{(1+\tau)^{2}} \frac{\log R}{R} \\
B_{0}=1 . & B_{1}=0
\end{array}
$$

with $R=r^{n}$, and $\epsilon$ a constant of integration that turns out to be the energy density.

## Bjorken Flow in large dimensions $d=n+1$

We have calculated these corrections to order $O\left(n^{-3}\right)$. At leading and subleading order they are given by,

$$
\begin{array}{ll}
S_{0}=1, & S_{1}=0 \\
A_{0}=1-\frac{\epsilon}{(1+\tau)} \frac{1}{R}, & A_{1}=\frac{\epsilon \log (1+\tau)}{(1+\tau)} \frac{1}{R}-\frac{\epsilon}{(1+\tau)^{2}} \frac{\log R}{R}, \\
B_{0}=1 . & B_{1}=0 .
\end{array}
$$

with $R=r^{n}$, and $\epsilon$ a constant of integration that turns out to be the energy density.

## Bjorken Flow in large dimensions $d=n+1$

We have calculated these corrections to order $O\left(n^{-3}\right)$. At leading and subleading order they are given by,

$$
\begin{array}{ll}
S_{0}=1, & S_{1}=0 \\
A_{0}=1-\frac{\epsilon}{(1+\tau)} \frac{1}{R}, & A_{1}=\frac{\epsilon \log (1+\tau)}{(1+\tau)} \frac{1}{R}-\frac{\epsilon}{(1+\tau)^{2}} \frac{\log R}{R} \\
B_{0}=1 . & B_{1}=0 .
\end{array}
$$

with $R=r^{n}$, and $\epsilon$ a constant of integration that turns out to be the energy density.

We know how to read off the energy density corresponding to this solution, which gives ideal and viscous Hydrodynamics to $2^{\text {nd }}$ order.

$$
\begin{equation*}
\epsilon(\tau)=\frac{\epsilon}{\tau}-\frac{\epsilon}{n}\left(\frac{\log \tau}{\tau}+\frac{2}{\tau^{2}}-\frac{1}{2} \frac{1}{\tau^{3}}\right)+O\left(n^{-2}\right) \tag{10}
\end{equation*}
$$

## Bjorken Flow in large dimensions $d=n+1$

We have calculated these corrections to order $O\left(n^{-3}\right)$. At leading and subleading order they are given by,

$$
\begin{array}{ll}
S_{0}=1, & S_{1}=0 \\
A_{0}=1-\frac{\epsilon}{(1+\tau)} \frac{1}{R}, & A_{1}=\frac{\epsilon \log (1+\tau)}{(1+\tau)} \frac{1}{R}-\frac{\epsilon}{(1+\tau)^{2}} \frac{\log R}{R} \\
B_{0}=1 . & B_{1}=0 .
\end{array}
$$

with $R=r^{n}$, and $\epsilon$ a constant of integration that turns out to be the energy density.

We know how to read off the energy density corresponding to this solution, which gives ideal and viscous Hydrodynamics to $2^{\text {nd }}$ order.

$$
\begin{equation*}
\epsilon(\tau)=\frac{\epsilon}{\tau}-\frac{\epsilon}{n}\left(\frac{\log \tau}{\tau}+\frac{2}{\tau^{2}}-\frac{1}{2} \frac{1}{\tau^{3}}\right)+O\left(n^{-2}\right) \tag{11}
\end{equation*}
$$

## Bjorken Flow in large dimensions $d=n+1$

We have calculated these corrections to order $O\left(n^{-3}\right)$. At leading and subleading order they are given by,

$$
\begin{array}{ll}
S_{0}=1, & S_{1}=0 \\
A_{0}=1-\frac{\epsilon}{(1+\tau)} \frac{1}{R}, & A_{1}=\frac{\epsilon \log (1+\tau)}{(1+\tau)} \frac{1}{R}-\frac{\epsilon}{(1+\tau)^{2}} \frac{\log R}{R} \\
B_{0}=1 . & B_{1}=0 .
\end{array}
$$

with $R=r^{n}$, and $\epsilon$ a constant of integration that turns out to be the energy density.

We know how to read off the energy density corresponding to this solution, which gives ideal and viscous Hydrodynamics to $2^{\text {nd }}$ order.

$$
\begin{equation*}
\epsilon(\tau)=\frac{\epsilon}{\tau}-\frac{\epsilon}{n}\left(\frac{\log \tau}{\tau}+\frac{2}{\tau^{2}}-\frac{1}{2} \frac{1}{\tau^{3}}\right)+O\left(n^{-2}\right) \tag{12}
\end{equation*}
$$

## Conclusion

- Why does Hydrodynamics work outside it's regime of applicability?
- Our estimate of this regime relies on the series converging, which it does not.
- All you can do to justify hydrodynamics is to resum the series and compare to truncations.
- What qualitative changes do we observe as we interpolate between gauge theories at infinite and finite coupling?
- At finite coupling our microscopic theory gains a dissipative mode, compatible with kinetic theory.
- Comparing the full resummation to the truncated series, $1^{\text {st }}$ order viscous hydro works very well in all cases.
- Can the large dimension limit be used to study Bjorken Flow in $n=4$ ?
- We have an anayltic solution that seems to reproduce the first few terms of Hydrodynamics.


## Back up slides

## Hydrodynamics in 3+1 Dimensions

The equation of motion for Hydrodynamics is the conservation equation

$$
\begin{equation*}
\nabla_{\mu} T^{\mu \nu}=0 \tag{13}
\end{equation*}
$$

where $T^{\mu \nu}=T^{\mu \nu}\left(\epsilon, P, u^{\mu}\right)$ with $\epsilon$ the energy density, $P$ the Pressure, and $u^{\mu}$ the fluid velocity.

## Hydrodynamics in 3+1 Dimensions

The equation of motion for Hydrodynamics is the conservation equation

$$
\begin{equation*}
\nabla_{\mu} T^{\mu \nu}=0 \tag{13}
\end{equation*}
$$

where $T^{\mu \nu}=T^{\mu \nu}\left(\epsilon, P, u^{\mu}\right)$ with $\epsilon$ the energy density, $P$ the Pressure, and $u^{\mu}$ the fluid velocity. For a perfect fluid

$$
\begin{equation*}
T_{\text {ideal }}^{\mu \nu}=\left(\epsilon_{0}+P_{0}\right) u^{\mu} u^{\nu}-P_{0} \eta^{\mu \nu} . \tag{14}
\end{equation*}
$$

## Hydrodynamics in 3+1 Dimensions

The equation of motion for Hydrodynamics is the conservation equation

$$
\begin{equation*}
\nabla_{\mu} T^{\mu \nu}=0 \tag{13}
\end{equation*}
$$

where $T^{\mu \nu}=T^{\mu \nu}\left(\epsilon, P, u^{\mu}\right)$ with $\epsilon$ the energy density, $P$ the Pressure, and $u^{\mu}$ the fluid velocity. For a perfect fluid

$$
\begin{equation*}
T_{\text {ideal }}^{\mu \nu}=\left(\epsilon_{0}+P_{0}\right) u^{\mu} u^{\nu}-P_{0} \eta^{\mu \nu} . \tag{14}
\end{equation*}
$$

For a non-ideal fluid, we include every possible tensor combination of $\partial^{\mu}$, $u^{\mu}$ and $\eta^{\mu \nu}$ with coefficients $c_{i}$.

## Hydrodynamics in 3+1 Dimensions

The equation of motion for Hydrodynamics is the conservation equation

$$
\begin{equation*}
\nabla_{\mu} T^{\mu \nu}=0 \tag{13}
\end{equation*}
$$

where $T^{\mu \nu}=T^{\mu \nu}\left(\epsilon, P, u^{\mu}\right)$ with $\epsilon$ the energy density, $P$ the Pressure, and $u^{\mu}$ the fluid velocity. For a perfect fluid

$$
\begin{equation*}
T_{\text {ideal }}^{\mu \nu}=\left(\epsilon_{0}+P_{0}\right) u^{\mu} u^{\nu}-P_{0} \eta^{\mu \nu} . \tag{14}
\end{equation*}
$$

For a non-ideal fluid, we include every possible tensor combination of $\partial^{\mu}$, $u^{\mu}$ and $\eta^{\mu \nu}$ with coefficients $c_{i}$.

$$
\begin{equation*}
T^{\mu \nu}=T_{\text {ideal }}^{\mu \nu}+c_{1} \partial^{\mu} u^{\nu}+c_{2} \partial^{\nu} u^{\mu}+c_{3} \eta^{\mu \nu} \partial_{\alpha} u^{\alpha}+c_{4} u^{\mu} u^{\nu} \partial_{\alpha} u^{\alpha}+\ldots \tag{15}
\end{equation*}
$$

## Hydrodynamics in 3+1 Dimensions

When $\partial u$ is small we can order the series in derivatives of $u^{\mu}$

$$
\begin{equation*}
T^{\mu \nu}=T_{\text {ideal }}^{\mu \nu}+O\left(\sim \partial^{\mu} u^{\nu}\right)+O\left(\sim\left(\partial^{\mu} u^{\nu}\right)^{2}\right)+\ldots \tag{16}
\end{equation*}
$$

- This series is known as the Gradient Expansion.


## Hydrodynamics in 3+1 Dimensions

When $\partial u$ is small we can order the series in derivatives of $u^{\mu}$

$$
\begin{equation*}
T^{\mu \nu}=T_{i d e a l}^{\mu \nu}+O\left(\sim \partial^{\mu} u^{\nu}\right)+O\left(\sim\left(\partial^{\mu} u^{\nu}\right)^{2}\right)+\ldots \tag{16}
\end{equation*}
$$

- This series is known as the Gradient Expansion.
- The coefficients $c_{i}$ are known as transport coefficients and uniquely specify our theory.


## The Fluid-Gravity correspondence

We can perform classical gravity calculations to find strongly coupled QFT results.


## Gravity Solution

Figure: Some Gauge theories are Gravity theories are conjectured to be the same theory under a field redefinition.

## The Fluid-Gravity correspondence

We can construct a dynamical gravity solution which will be dual to Bjorken Flow for $\mathrm{N}=4 \mathrm{SYM}$ :


Figure: Some Gauge theories and Gravity theories are conjectured to be the same theory under a field redefinition.

